

$$7.1.1: u'' + 0.5u' + 2u = 0 \quad \begin{array}{l} u' = v \\ v' = u'' \end{array}$$

$$\Rightarrow \begin{array}{l} u' = v \\ v' = -0.5v - 2u \end{array}$$

$$7.1.2: u'' + 0.5u' + 2u = 3\sin t \quad u' = v, v' = u''$$

$$\Rightarrow \begin{array}{l} u' = v \\ v' = -2u - 0.5v + 3\sin t \end{array}$$

$$7.1.3: t^2 u'' + t u' + (t^2 - 25)u = 0 \quad u' = v, v' = u''$$

$$\Rightarrow \begin{array}{l} u' = v \\ v' = -\left(1 - \frac{25}{t^2}\right)u - \frac{1}{t}v \end{array}$$

$$7.1.4: u^{(4)} - u = 0 \Rightarrow \begin{array}{l} u' = v \\ v' = w \\ w' = x \\ x' = u \end{array}$$

$$7.1.7: \begin{array}{l} x_1' = -2x_1 + x_2 \\ x_2' = x_1 - 2x_2 \end{array}$$

$$a) \begin{array}{l} x_2 = 2x_1 + x_1' \\ x_2' = 2x_1' + x_1'' = -2(2x_1 + x_1') + x_1 \end{array}$$

$$\Rightarrow x_1'' + 4x_1' + 3x_1 = 0$$

$$x_1 = c e^{rt} \Rightarrow c e^{rt} (r^2 + 4r + 3) = 0$$

$$r = -3, -1$$

$$\Rightarrow x_1 = c_1 e^{-3t} + c_2 e^{-t}$$

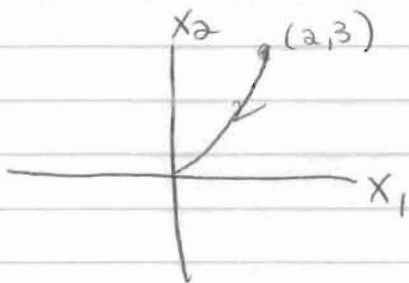
$$\begin{aligned} x_2 &= 2x_1 + x_1' = 2c_1 e^{-3t} + 2c_2 e^{-t} - 3c_1 e^{-3t} - c_2 e^{-t} \\ &= -c_1 e^{-3t} + c_2 e^{-t} \end{aligned}$$

$$7.1.7b: \begin{aligned} x_1(0) &= 2 = c_1 \cdot 1 + c_2 \cdot 1 \\ x_2(0) &= 3 = -c_1 \cdot 1 + c_2 \cdot 1 \\ \hline 5 &= 0 + 2c_2 \Rightarrow c_2 = \frac{5}{2} \\ &\Rightarrow c_1 = -\frac{1}{2} \end{aligned}$$

$$x_1(t) = -\frac{1}{2}e^{-3t} + \frac{5}{2}e^{-t}$$

$$x_2(t) = \frac{1}{2}e^{-3t} + \frac{5}{2}e^{-t}$$

7.1.7.c:



$$7.1.8: \begin{aligned} x_1' &= 3x_1 - 2x_2 & x_1(0) &= 3 \\ x_2' &= 2x_1 - 2x_2 & x_2(0) &= \frac{1}{2} \end{aligned}$$

$$\Rightarrow \frac{3}{2}x_1' - \frac{1}{2}x_1'' = 2x_1 - 3x_1 + x_1'$$

$$\Rightarrow 0 = x_1'' - x_1' - 2x_1$$

$$0 = r^2 - r - 2 = (r-2)(r+1); r=2, -1$$

$$x_1 = c_1 e^{2t} + c_2 e^{-t}$$

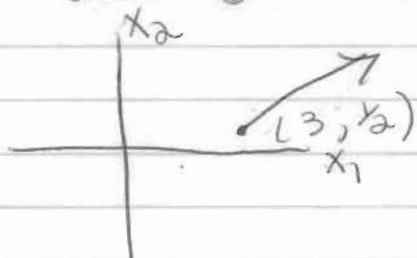
$$x_2 = \frac{3}{2}c_1 e^{2t} + \frac{3}{2}c_2 e^{-t} - c_1 e^{2t} + \frac{1}{2}c_2 e^{-t} = \frac{1}{2}c_1 e^{2t} + c_2 e^{-t}$$

$$3 = c_1 + c_2$$

$$\frac{1}{2} = \frac{1}{2}c_1 + c_2 \Rightarrow 1 = c_1 + 2c_2 \Rightarrow 2 = -3c_2 \Rightarrow c_2 = -\frac{2}{3}, c_1 = \frac{11}{3}$$

$$x_1(t) = \frac{11}{3}e^{2t} - \frac{2}{3}e^{-t}$$

$$x_2(t) = \frac{11}{6}e^{2t} - \frac{4}{3}e^{-t}$$



$$7.1.9: \begin{cases} x_1' = \frac{5}{4}x_1 + \frac{3}{4}x_2 \\ x_2' = \frac{3}{4}x_1 + \frac{5}{4}x_2 \end{cases} \quad \begin{matrix} x_1(0) = -2 \\ x_2(0) = 1 \end{matrix}$$

$$x_2 = \frac{1}{3}x_1' - \frac{5}{3}x_1$$

$$\Rightarrow \frac{1}{3}x_1'' - \frac{5}{3}x_1' = \frac{3}{4}x_1 + \frac{5}{3}x_1' - \frac{25}{12}x_1$$

$$\Rightarrow x_1'' - \frac{5}{2}x_1' + x_1 = 0 \Rightarrow x = ce^{rt}, \quad r^2 - \frac{5}{2}r + 1 = 0$$

$$\Rightarrow (r-2)(r-\frac{1}{2}) = 0 \quad r = 2, \frac{1}{2}$$

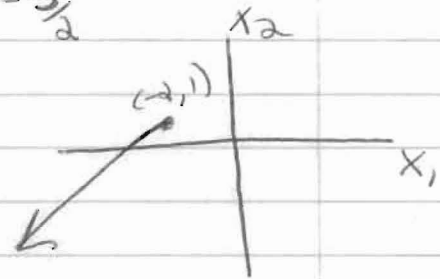
$$x_1(t) = c_1 e^{2t} + c_2 e^{\frac{1}{2}t} \quad ; \quad x_2(t) = \frac{2}{3}c_1 e^{2t} + \frac{1}{3}c_2 e^{\frac{1}{2}t} - \frac{5}{3}c_1 e^{2t} - \frac{5}{3}c_2 e^{\frac{1}{2}t}$$

$$x_2(t) = c_1 e^{2t} - c_2 e^{\frac{1}{2}t}$$

$$\begin{cases} -2 = c_1 + c_2 \\ 1 = c_1 - c_2 \end{cases} \Rightarrow c_1 = -\frac{1}{2}, c_2 = -\frac{3}{2}$$

$$x_1(t) = -\frac{1}{2}e^{2t} - \frac{3}{2}e^{\frac{1}{2}t}$$

$$x_2(t) = -\frac{1}{2}e^{2t} + \frac{3}{2}e^{\frac{1}{2}t}$$



$$7.1.10: \begin{cases} x_1' = x_1 - 2x_2 \\ x_2' = 3x_1 - 4x_2 \end{cases} \quad \begin{matrix} x_1(0) = -1 \\ x_2(0) = 2 \end{matrix}$$

$$x_2 = \frac{1}{2}x_1 - \frac{1}{2}x_1'$$

$$\Rightarrow \frac{1}{2}x_1' - \frac{1}{2}x_1'' = 3x_1 - 2x_1 + 2x_1'$$

$$\Rightarrow 0 = \frac{1}{2}x_1'' + \frac{3}{2}x_1' + x_1 \Rightarrow 0 = x_1'' + 3x_1' + 2x_1$$

$$r^2 + 3r + 2 = 0 \Rightarrow (r+2)(r+1) = 0, \quad x = ce^{rt}$$

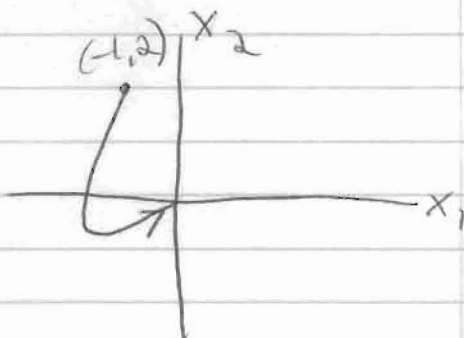
$$x_1(t) = c_1 e^{-t} + c_2 e^{-2t} \quad ; \quad x_2(t) = \frac{c_1}{2} e^{-t} + \frac{c_2}{2} e^{-2t} + \frac{c_1}{2} e^{-t} + c_2 e^{-2t}$$

$$x_2(t) = c_1 e^{-t} + \frac{3}{2}c_2 e^{-2t}$$

$$\begin{cases} -1 = c_1 + c_2 \\ 2 = c_1 + \frac{3}{2}c_2 \end{cases} \Rightarrow c_2 = 0, c_1 = -1$$

$$x_1(t) = -e^{-t}$$

$$x_2(t) = -e^{-t}$$



$$7.1.11: \begin{cases} x_1' = 2x_2 \\ x_2' = -2x_1 \end{cases} \Rightarrow \frac{1}{2} x_1'' = -2x_1 \Rightarrow x_1'' + 4x_1 = 0$$

$$x = ce^{rt} \Rightarrow r^2 + 4 = 0$$

$$r = \pm 2i$$

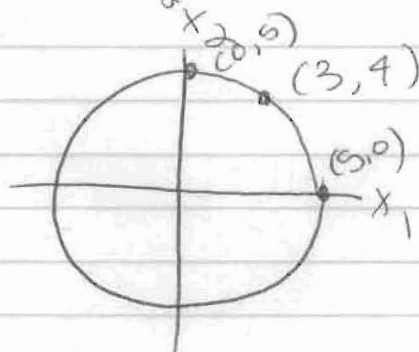
$$x_1(t) = c_1 \cos 2t + c_2 \sin 2t$$

$$e^{2i} = \cos 2t + i \sin 2t$$

$$x_2(t) = -1 \cdot c_1 \sin 2t + c_2 \cos 2t$$

$$x_1(0) = 3 = c_1 \quad x_1(t) = 3 \cos 2t + 4 \sin 2t$$

$$x_2(0) = 4 = c_2 \quad x_2(t) = 4 \cos 2t - 3 \sin 2t$$



$$7.1.12: \begin{cases} x_1' = -5x_1 + 2x_2 \\ x_2' = -2x_1 - 5x_2 \end{cases} \quad \begin{matrix} x_1(0) = -2 \\ x_2(0) = 2 \end{matrix}$$

$$x_2 = \frac{1}{2} x_1' + \frac{1}{4} x_1$$

$$\Rightarrow \frac{1}{2} x_1'' + \frac{1}{4} x_1' = -2x_1 - \frac{1}{4} x_1' - \frac{1}{8} x_1$$

$$\Rightarrow 4x_1'' + 2x_1' = -16x_1 - 2x_1' - x_1$$

$$\Rightarrow 4x_1'' + 4x_1' + 17x_1 = 0$$

$$\Rightarrow 4r^2 + 4r + 17 = 0 \Rightarrow r = \frac{-4 \pm \sqrt{16 - 4(4)(17)}}{8}$$

$$\Rightarrow r = \frac{-4 \pm \sqrt{-256}}{8} = -\frac{1}{2} \pm 2i, \quad x = ce^{rt}$$

$$x_1 = c_1 e^{-\frac{1}{2}t} \cos(2t) + c_2 e^{-\frac{1}{2}t} \sin(2t)$$

$$x_2 = \frac{c_1}{2} \cdot \left(-\frac{1}{2}\right) e^{-\frac{1}{2}t} \cos(2t) + \frac{c_1}{2} e^{-\frac{1}{2}t} (2 \sin(2t))$$

$$+ \frac{c_2}{2} \cdot \left(-\frac{1}{2}\right) e^{-\frac{1}{2}t} \sin(2t) + \frac{c_2}{2} e^{-\frac{1}{2}t} (2 \cos(2t))$$

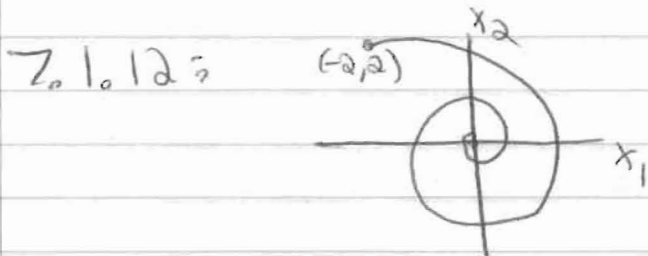
$$+ \frac{c_1}{4} e^{-\frac{1}{2}t} \cos(2t) + \frac{c_2}{4} e^{-\frac{1}{2}t} \sin(2t)$$

$$= e^{-\frac{1}{2}t} \cos(2t) \left(-\frac{c_1}{4} + c_2 + \frac{c_1}{4}\right) + e^{-\frac{1}{2}t} \sin(2t) \left(-c_1 - \frac{c_2}{4} + \frac{c_2}{4}\right)$$

$$= c_2 e^{-\frac{1}{2}t} \cos(2t) - c_1 e^{-\frac{1}{2}t} \sin(2t)$$

$$-2 = c_1 \Rightarrow x_1(t) = -2e^{-\frac{1}{2}t} \cos(2t) + 2e^{-\frac{1}{2}t} \sin(2t)$$

$$2 = c_2 \Rightarrow x_2(t) = 2e^{-\frac{1}{2}t} \cos(2t) + 2e^{-\frac{1}{2}t} \sin(2t)$$



7.1.22: a)  $Q_1'(t) = 1 \cdot 1.5 - \frac{3}{30}Q_1 + \frac{1.5}{20}Q_2$   $Q_1(0) = 25$   
 $Q_2'(t) = 3 \cdot 1 + \frac{3}{30}Q_1 - \frac{4}{20}Q_2$   $Q_2(0) = 15$

$\Rightarrow Q_1'(t) = \frac{3}{2} - \frac{1}{10}Q_1 + \frac{3}{40}Q_2$

$Q_2'(t) = 3 + \frac{1}{10}Q_1 - \frac{1}{5}Q_2$

b)  $Q_1'(t) = 0 = \frac{3}{2} - \frac{1}{10}Q_1^E + \frac{3}{40}Q_2^E$

$Q_2'(t) = 0 = 3 + \frac{1}{10}Q_1^E - \frac{1}{5}Q_2^E$

$\Rightarrow 0 = \frac{3}{2} - \frac{3}{40}Q_2^E \Rightarrow Q_2^E = \frac{3}{2} \cdot \frac{40}{3} = 36$

$0 = \frac{3}{2} - \frac{1}{10}Q_1^E + \frac{3}{10} \cdot 36 \Rightarrow \frac{1}{10}Q_1^E = \frac{3}{2} + \frac{27}{10}$

$\Rightarrow Q_1^E = 42$ ,  $Q_2$  will be faster

c)  $x_1 = Q_1(t) - Q_1^E \Rightarrow x_1' = Q_1'(t)$

$x_2 = Q_2(t) - Q_2^E \Rightarrow x_2' = Q_2'(t)$

$x_1' = \frac{3}{2} - \frac{1}{10}(x_1 + Q_1^E) + \frac{3}{40}(x_2 + Q_2^E) = \frac{3}{2} - \frac{1}{10}x_1 - \frac{42}{10} + \frac{3}{40}x_2 + \frac{27}{10}$   
 $= \frac{15 + 27 - 42}{10} - \frac{1}{10}x_1 + \frac{3}{40}x_2 = -\frac{1}{10}x_1 + \frac{3}{40}x_2$

$x_2' = 3 + \frac{1}{10}(x_1 + Q_1^E) - \frac{1}{5}(x_2 + Q_2^E) = 3 + \frac{1}{10}x_1 + \frac{42}{10} - \frac{1}{5}x_2 - \frac{36}{5}$   
 $= \frac{30 + 42 - 36}{10} + \frac{1}{10}x_1 - \frac{1}{5}x_2 = \frac{1}{10}x_1 - \frac{1}{5}x_2$

$x_1(0) = Q_1(0) - Q_1^E = 25 - 42 = -17$

$x_2(0) = Q_2(0) - Q_2^E = 15 - 36 = -21$



$$Q_1'(t) = 3g_1 + \frac{1}{100} Q_2 - \frac{2+2}{60} Q_1 = 3g_1 + \frac{Q_2}{100} - \frac{Q_1}{15}$$

$$Q_2'(t) = g_2 + \frac{2}{60} Q_1 - \frac{1+2}{100} Q_2 = g_2 + \frac{Q_1}{30} - \frac{3}{100} Q_2$$

$$Q_1(0) = Q_1^0, \quad Q_2(0) = Q_2^0$$

b)  $0 = 3g_1 + \frac{1}{100} Q_2^E - \frac{1}{15} Q_1^E \Rightarrow 9g_1 + g_2 - \frac{5}{30} Q_1^E = 0$

$$0 = g_2 - \frac{3}{100} Q_2^E + \frac{1}{30} Q_1^E \Rightarrow Q_1^E = 54g_1 + 6g_2$$

$$0 = g_2 - \frac{3}{100} Q_2^E + \frac{54}{30} g_1 + \frac{6}{30} g_2$$

$$\Rightarrow Q_2^E = \frac{100}{3} \left( \frac{36}{30} g_2 + \frac{54}{30} g_1 \right) = 60g_1 + 40g_2$$

c) Only if  $60g_1 + 40g_2 = 50$   
 $54g_1 + 6g_2 = 60$

$$\begin{bmatrix} 60 & 40 \\ 54 & 6 \end{bmatrix} = A \quad \det(A) = 360 - 2160 \neq 0$$

$$A^{-1} = \begin{bmatrix} -\frac{1}{300} & \frac{1}{45} \\ \frac{2}{1100} & -\frac{1}{150} \end{bmatrix} \quad A^{-1}b = \begin{bmatrix} -\frac{1}{300} & \frac{1}{45} \\ \frac{2}{1100} & -\frac{1}{150} \end{bmatrix} \begin{bmatrix} 50 \\ 60 \end{bmatrix} = \begin{bmatrix} \frac{1}{6} \\ -\frac{1}{2} \end{bmatrix}$$

$g_2$  cannot be negative, so although the equation can be solved, the solution is not valid.

d) ①  $g_2 = \frac{Q_1^E}{6} - 9g_1$   
 ②  $g_2 = \frac{Q_2^E}{40} - \frac{3}{2}g_1$



The y-intercept of eq ① is  $\frac{Q_1^E}{6}$  and eq  $g_1$  ② is  $Q_2^E/40$ . The x-intercepts are  $\frac{Q_1^E}{54}$  and  $\frac{Q_2^E}{60}$ .

There is a unique <sup>valid</sup> soln as long as  $\frac{Q_1^E}{54} \leq \frac{Q_2^E}{60}$  or  $\frac{Q_2^E}{40} \leq \frac{Q_1^E}{6}$ , i.e.  $10/9 \leq \frac{Q_2}{Q_1} \leq \frac{20}{3}$