

# REPORT OF ENTROPY-BASED NONLINEAR VISCOSITY FOR CONSERVATION LAWS

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Jean-Luc Guermond et.al proposed an entropy-based nonlinear viscosity ([2, 3]) to solve hyperbolic equations.

## 1. ALGORITHM

We consider the hyperbolic equation

$$\partial_t u + \nabla \cdot \mathbf{f}(u) = 0, \quad u(\mathbf{x}, 0) = u_0(\mathbf{x}), \quad \mathbf{x} \in \Omega, t > 0 \quad (1)$$

subject to appropriate boundary conditions. It is well know that Cauchy or the initial boundary value problem has a unique entropy solution satisfying

$$\partial_t E(u) + \nabla \cdot \mathbf{F}(u) \leq 0, \quad (2)$$

where entropy  $E(u)$  is a convex function and  $\mathbf{F}(u) = \int E'(u) \mathbf{f}'(u) du$  is the entropy flux. The idea of the entropy-based nonlinear viscosity is to construct viscosity through the entropy residual:

$$D(x, t) = \partial_t E(u(x, t)) + \nabla \cdot \mathbf{F}(u(x, t)), \mathbf{x} \in \Omega, t > 0. \quad (3)$$

Let  $u_h(\cdot, t)$  be the numerical approximation of the exact solution  $u$  at time  $t$  (and similarly subscript  $h$  denote the approximation of the variables). The entropy viscosity method comprises of the following steps ([3]):

- (1) Given an entropy pair  $(E, \mathbf{F})$ , define the entropy residual:

$$D(x, t) = \partial_t E(u(x, t)) + \nabla \cdot \mathbf{F}(u(x, t)), \mathbf{x} \in \Omega, t > 0.$$

- (2) Use this residual to define a viscosity, say  $\nu_E$

$$\nu_E(\mathbf{x}, t) = c_E h^2(\mathbf{x}) R(D_h(\cdot, t)) / \|E(u_h) - \bar{E}(u_h)\|_{\infty, \Omega},$$

where  $h(\mathbf{x})$  is the local mesh size at  $\mathbf{x} \in \Omega$ ,  $\bar{E}$  is the space-averaged value of the entropy,  $c_E$  is a tunable constant and  $R$  is a positive function to be decided ( $R(D_h) = |D_h|$  in this report and also in [2, 3]).

- (3) Introduce an upper bound to the entropy viscosity:

$$\nu_{\max}(\mathbf{x}, t) = c_{\max} h_{\max} \max_{\mathbf{y} \in V_x} |\mathbf{f}'(u(\mathbf{y}, t))|.$$

Here  $V_x$  is a yet to be defined neighborhood of  $\mathbf{x}$ ,  $\mathbf{f}'(u(\mathbf{y}, t))$  is the local wave speed.

- (4) Define the entropy viscosity:

$$\nu_h = S(\min(\nu_{\max}, \nu_E)),$$

where  $S$  is a yet to be defined smoothing operator that depends on the space approximation (the simplest case is  $S = I$ ).

- (5) Augment the discrete form of the conservation law (1) with the dissipation term  $-\nabla \cdot (\nu_h \nabla u_h)$  and make the viscosity explicit.

To conclude the equation we in fact solve is the advection-diffusion equation with artificial viscosity:

$$\partial_t u + \nabla \cdot \mathbf{f}(u) = \partial_x(\nu(u)\partial_x u). \quad (4)$$

At time step  $t_{k+1}$ , the viscosity  $\nu$  is made explicit and evaluated at time  $t_k$ .

This simple idea is *mesh and approximation independent* and can be applied to any equation or physical system supplemented with an entropy equation/inequality.

For time integral, the semi-discretized equation

$$\frac{d}{dt}U = L(U)$$

is solved with 3rd-order TVD Runge-Kutta (also called SSP Runge-Kutta [1]). To approximate  $\partial_t E(u)$ , second order finite difference is used:

$$\partial_t E^n \approx \frac{3E(u^n) - 4E(u^{n-1}) + E(u^{n-2})}{2\Delta t}, \quad n \geq 2.$$

For  $n = 1$  first order finite difference is used and for  $n = 0$  let  $\partial_t E = 0$ .

## 2. COMPUTATIONAL RESULTS

In this section we present two 1-D computational results:

- Burges equation with shock wave fully developed:

$$\begin{aligned} \partial_t u + \partial_x(u^2/2) &= 0, \quad x \in [0, L] \\ u(x, 0) &= \sin(2\pi x/L). \end{aligned}$$

The final time is  $T = L/4$ , which is 1/4 period.

- Long time evolution of transport equation.

$$\partial_t u + \partial_x u = 0, \quad x \in [0, 1]$$

with initial condition

$$u(x, 0) = \begin{cases} \exp(-300(2x - 0.3)^2) & |2x - 0.3| \leq 0.25, \\ 1 & |2x - 0.9| \leq 0.2, \\ (1 - (\frac{2x-1.6}{0.2})^2)^{1/2} & |2x - 1.6| \leq 0.2, \\ 0 & \text{otherwise.} \end{cases}$$

The final time is  $T = 100$  which is 100 period.

Figure 1 shows the initial condition and the final results for these two problems.

**2.1. Fourier collocation method.** For 1-D Burges equation, we set  $E(u) = u^2/2, R(D) = |D|, S = I$ . The result is shown in Fig. 2 Table 1 shows the convergence rates in  $L_1$  and  $L_2$  norm. We can see that for discontinuous problem the convergence rate in  $L_1$  norm is 1 and 0.5 in  $L_2$  norm.

TABLE 1.  $L_1$  and  $L_2$  error and the convergence rate of the solution of Burges equation

$h$	$L_1$	rate	$L_2$	rate
$2\pi/100$	1.551e-1	-	2.715e-1	-
$2\pi/200$	8.095e-2	0.94	1.967e-1	0.46
$2\pi/400$	4.305e-2	0.91	1.408e-1	0.48
$2\pi/800$	2.168e-2	0.99	9.928e-2	0.50

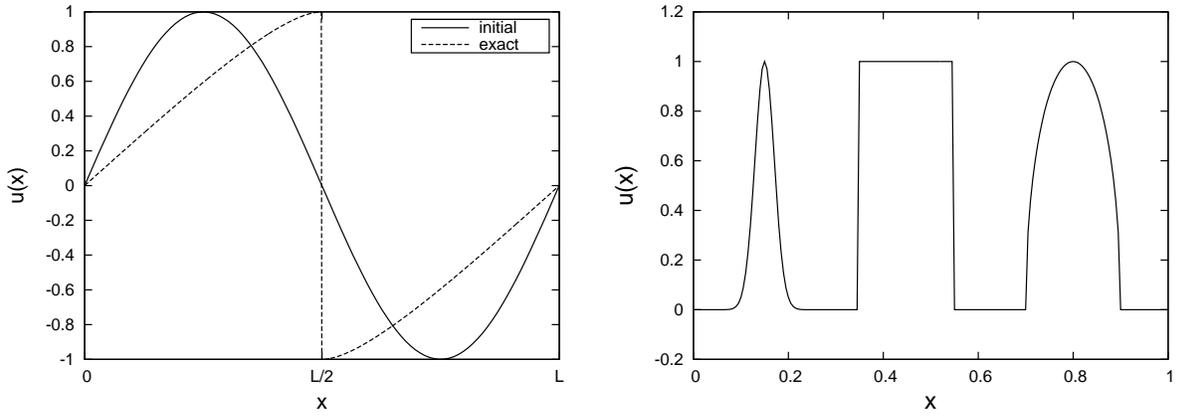


FIGURE 1. Initial condition and exact solution for Burgers equation (left) on  $[0, L]$  at  $T = L/4$  and transport equation (right) on  $[0, 1]$  at  $T = 100$ . For the transport equation the exact solution is the same as the initial condition so only one curve is shown.

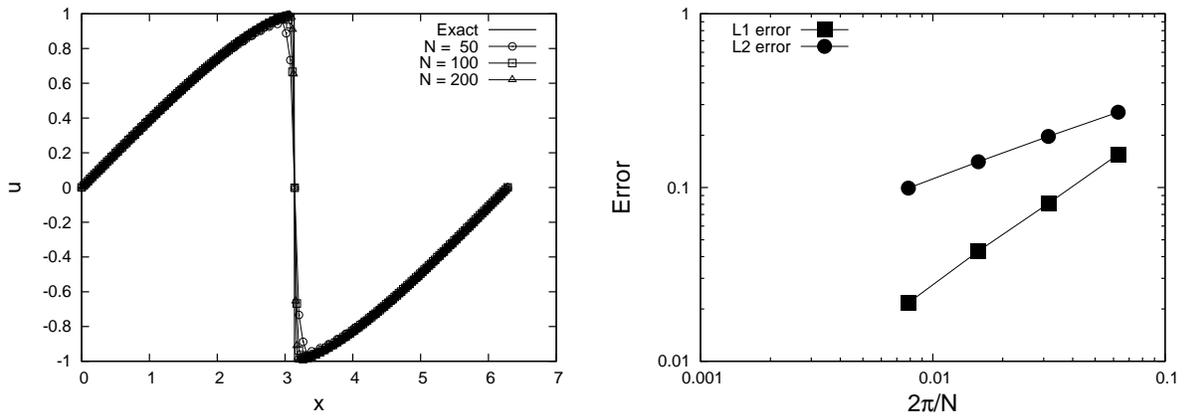


FIGURE 2. Left: Solution of Burgers equation on  $[0, 2\pi]$ .  $t = \pi/2$ ,  $\alpha_{\max} = 2/\pi$ ,  $\alpha = 0.1$ . Right:  $L_1$  and  $L_2$  error of the solution of Burgers equation on  $[0, 2\pi]$  with different  $h$ .

**2.2. Spectral element method.** The spectral element shape functions are the Lagrange polynomials based on the  $k + 1$  Gauss-Lobatto-Legendre points in 1D where  $k$  is the order of the polynomials. The quadrature points are based on the Gauss-Lobatto-Legendre points so that the interpolation points and quadrature points coincide. We compute the solution at  $t = 100$ , with  $k = 2, 4, 8$ . The mesh is composed of  $200/k$  cells so that the total number of degrees of freedom is 200. The parameters are set as  $c_{\max} = 0.1/k$ ,  $c_E = 1.0$ ,  $\Delta t = 0.1h_{\min}$ . We can see from left plot of Figure 3 that if we do not include viscosity there will be severe oscillations even with polynomial of order 8. In the right plot of Figure 3 results by viscosity is shown. We can observe that there is no oscillations in the result by using entropy-based viscosity.

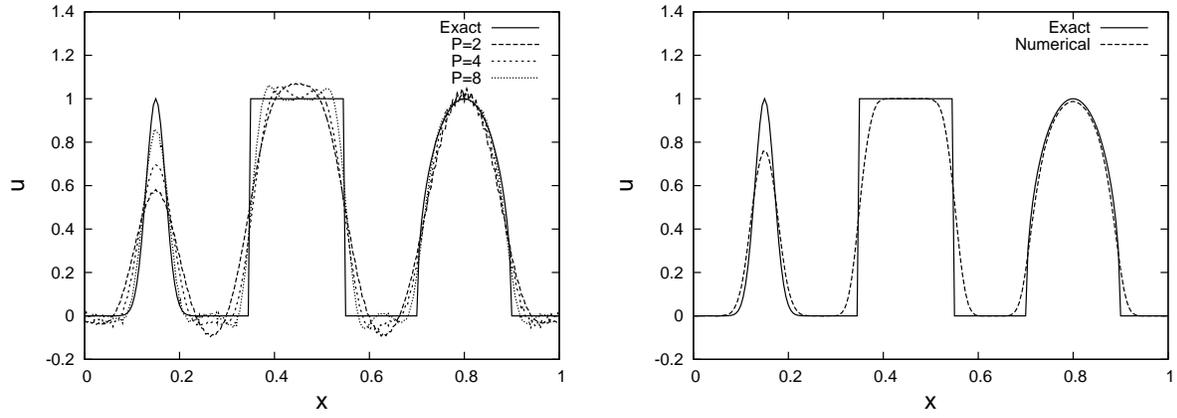


FIGURE 3. Solution of transport equation without viscosity (left) and with entropy-based viscosity (right). In the right plot  $k = 8$ .

#### REFERENCES

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